

Multimodal Biometrics

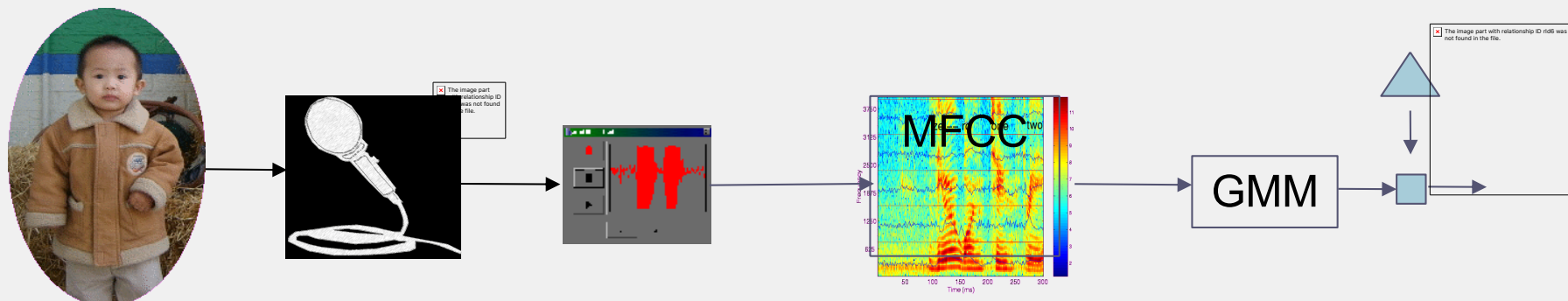
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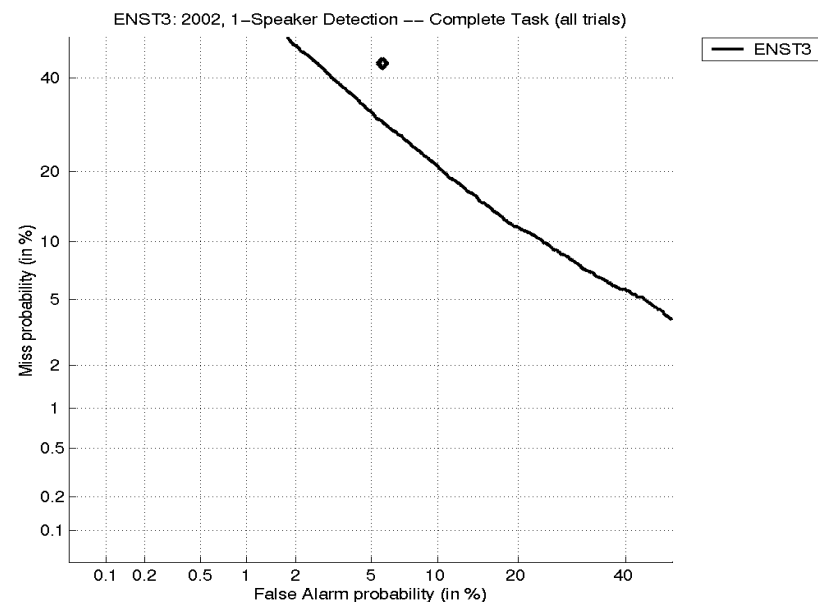
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Biometric authentication and Performance characterisation



- False rejection
- False acceptance
- Total error rate/Half total error rate
- Operating point
 - Equal error rate (civilian)
 - Zero false acceptance (high security forensic)
 - Zero false rejection (low risk banking)



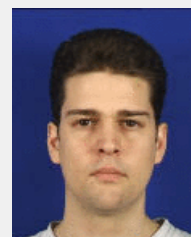
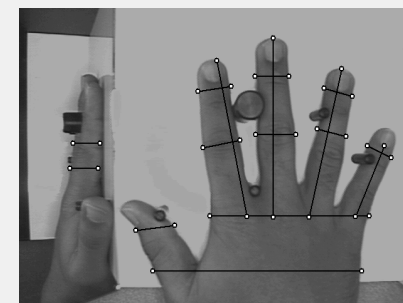
Multimodal biometrics

- Different biometric modalities developed

- finger print
- iris
- face (2D, 3D)
- voice
- hand
- lips dynamics
- gait

Different traits- different properties

- usability
- acceptability
- performance
- robustness in changing environment
- reliability
- applicability (different scenarios)



Benefits of multimodality

- Motivation for multiple biometrics
 - To enhance performance
 - To increase population coverage by reducing the failure to enroll rate
 - To improve resilience to spoofing
 - To permit choice of biometric modality for authentication
 - To extend the range of environmental conditions under which authentication can be performed

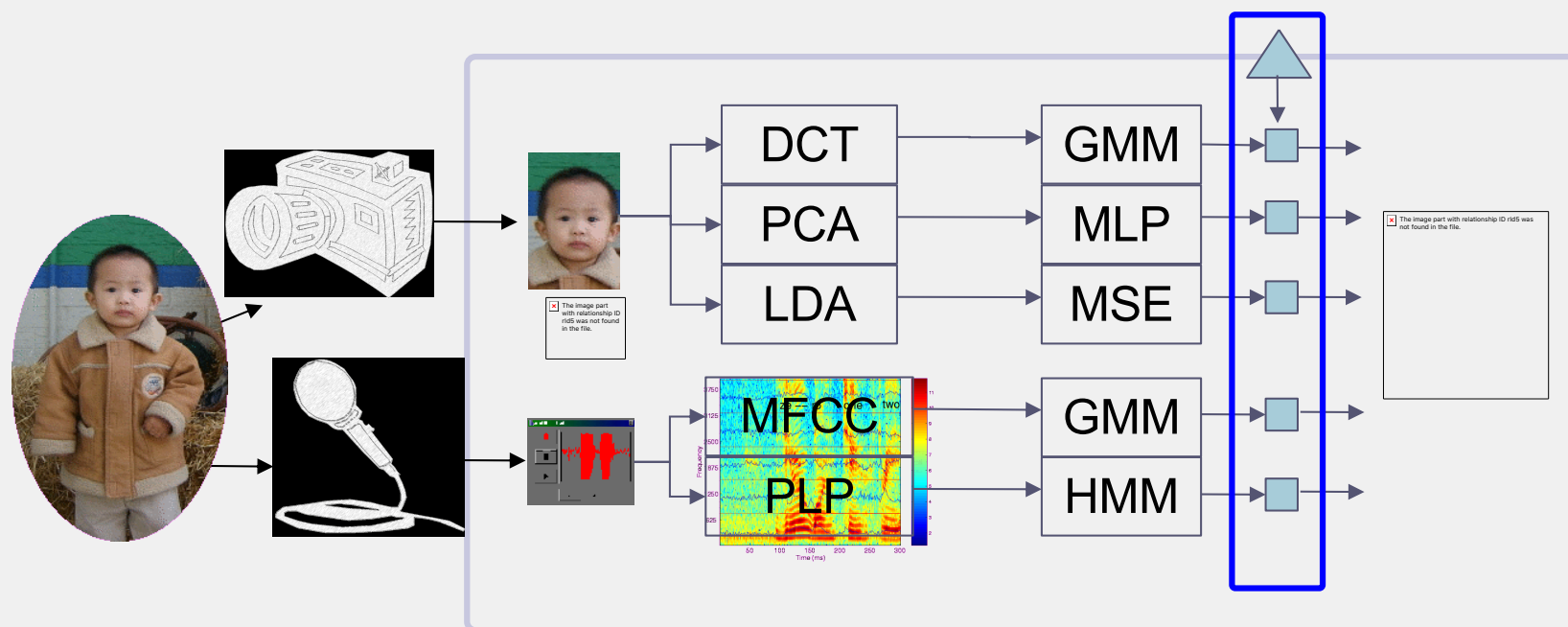
OUTLINE

- Fusion architectures
- Score level fusion: Problem formulation
- Estimation error
- Multiple expert paradigm
- Quality based fusion of biometric modalities
- Discussion and conclusions

Fusion architectures

- Integration of multiple biometric modalities
- Sensor (data) level fusion
 - Linear/nonlinear combination of registered variables
 - Representation space augmentation
- Feature level fusion
- Soft decision level fusion
- Decision level fusion

Decision level fusion



Legend



threshold



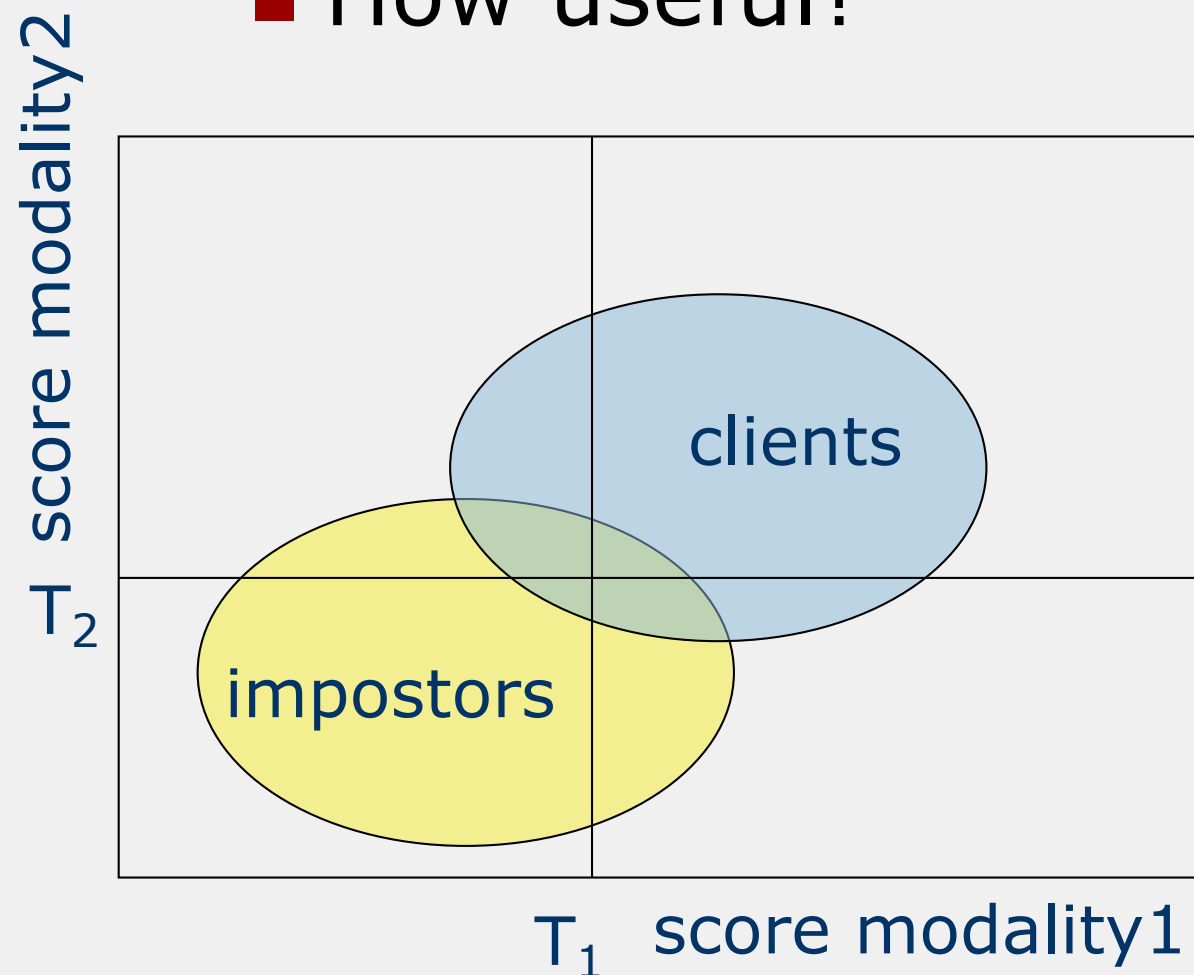
score

Data

Features

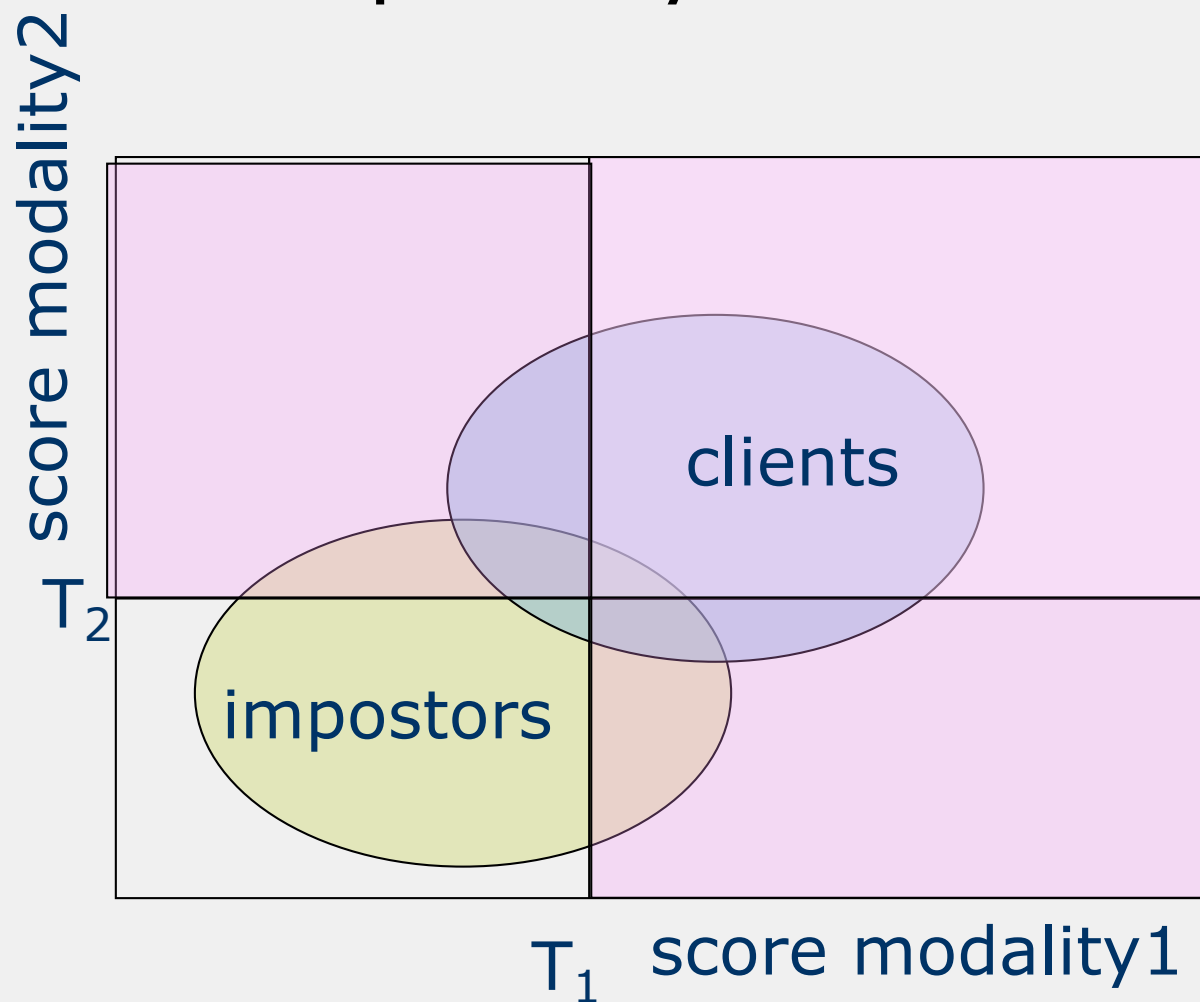
Decision-level fusion

■ How useful?



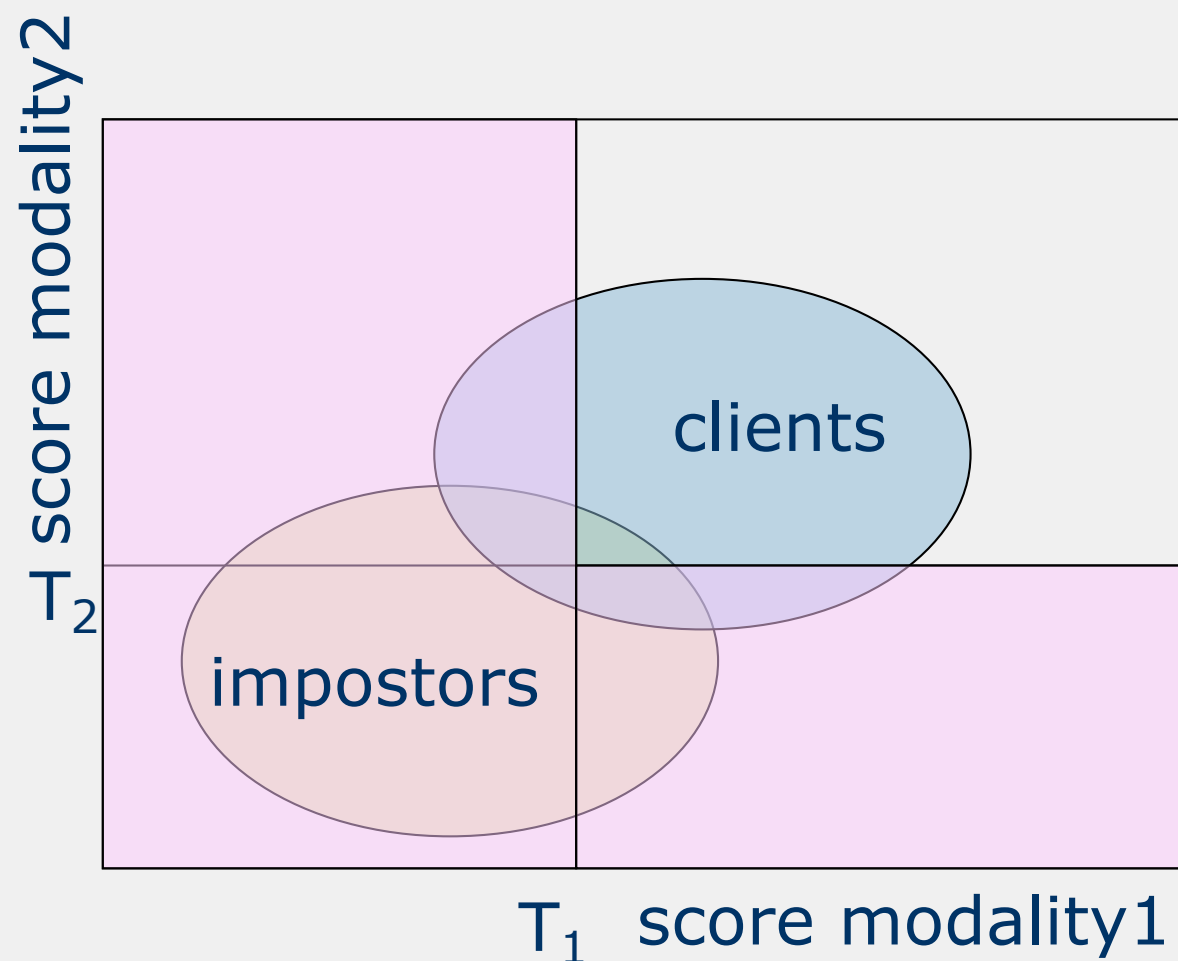
Decision-level fusion

- Accepted by either modality



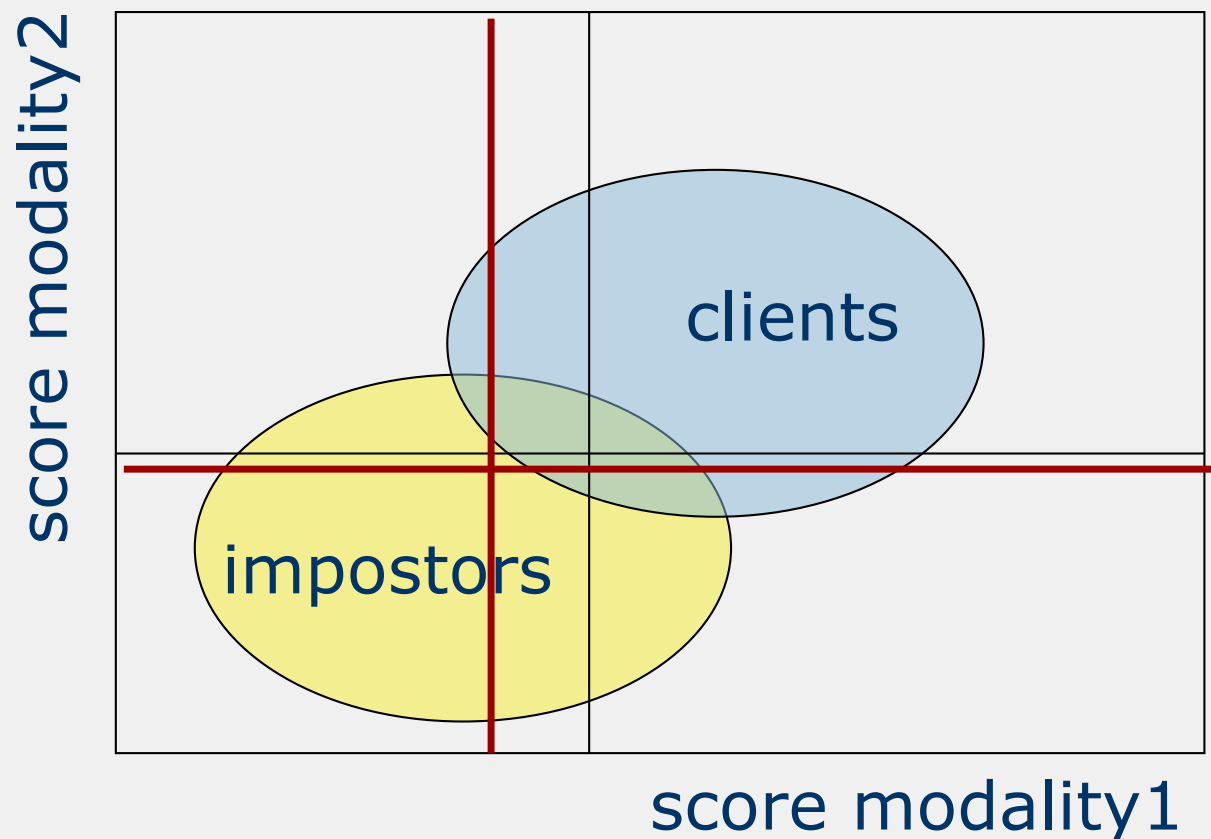
Decision-level fusion

- Accepted by both



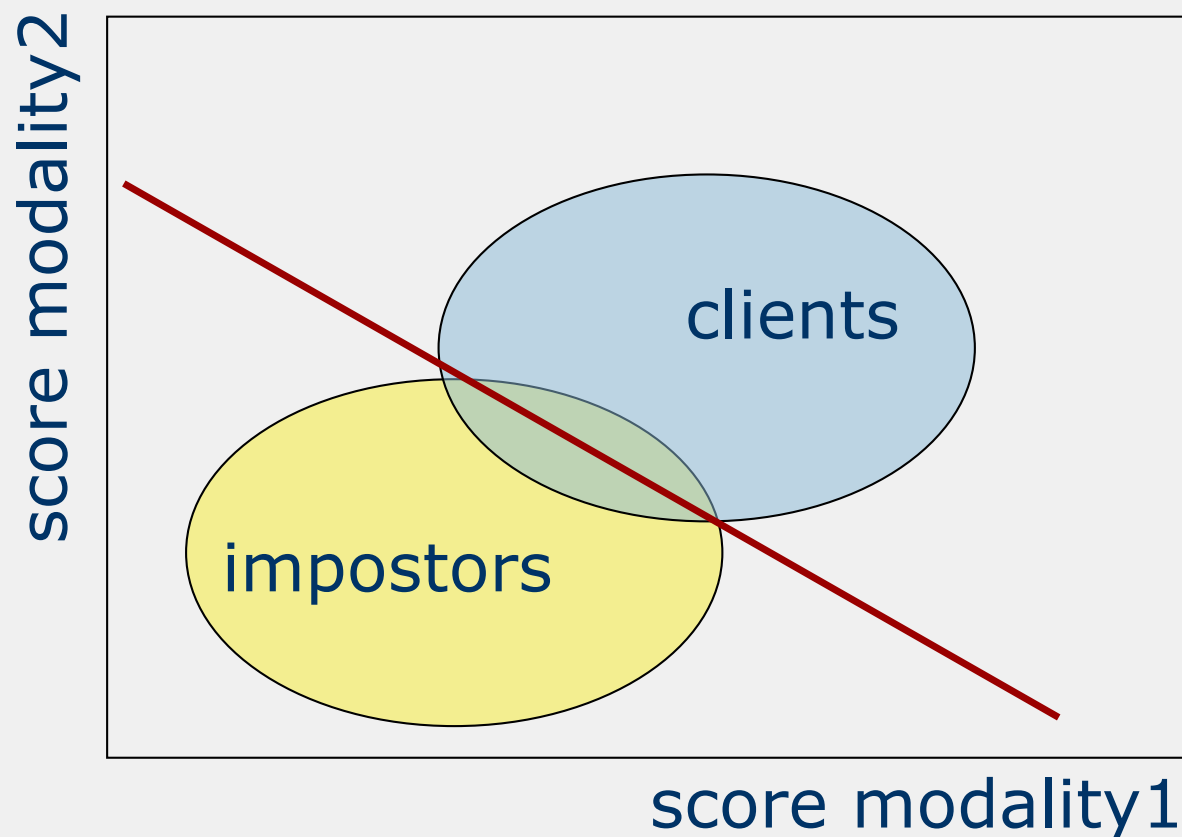
Decision-level fusion

Better performance by adapting the thresholds

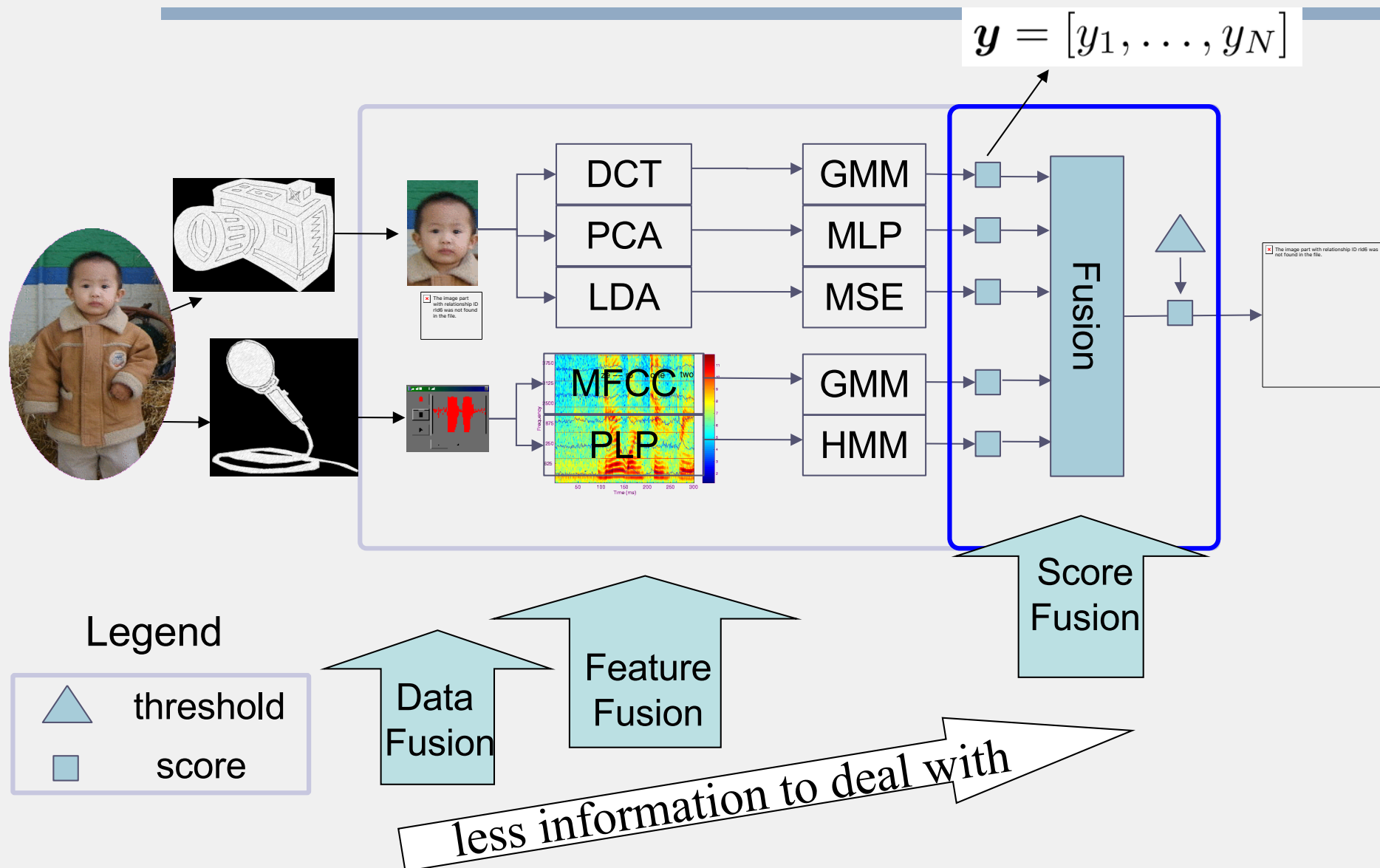


Score-level fusion

- Should improve performance

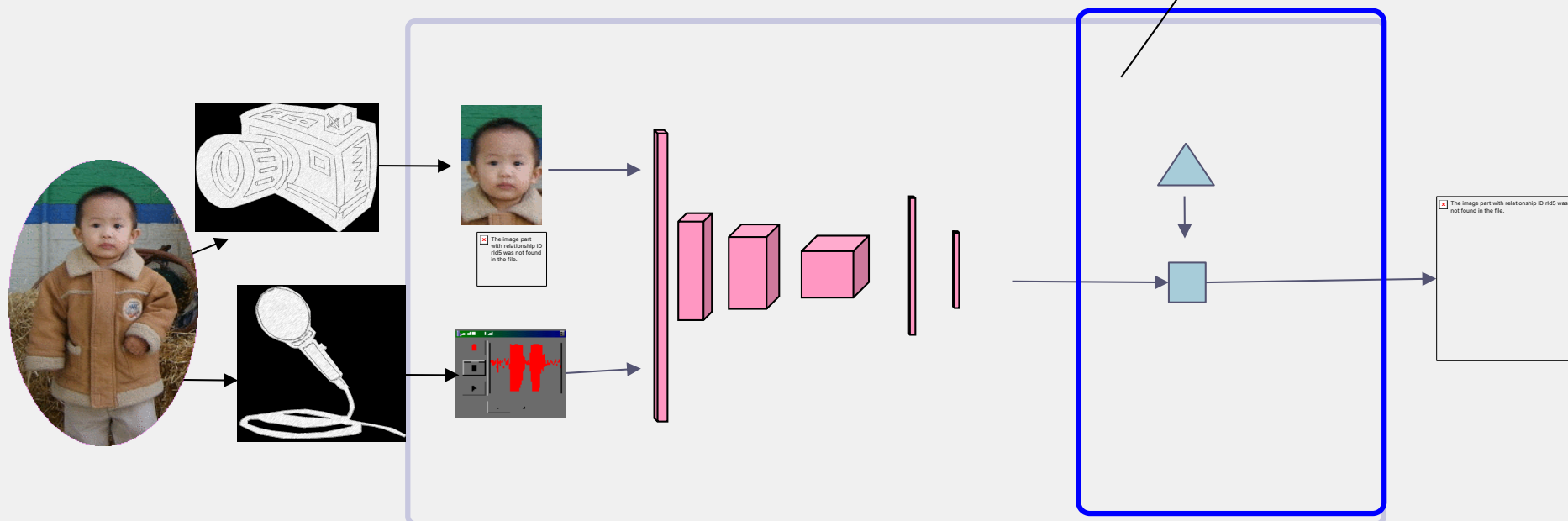


Levels of Fusion

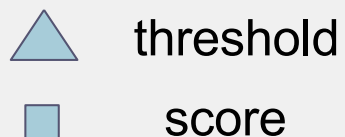


Data level fusion

$$\mathbf{y} = [y_1, \dots, y_N]$$



Legend

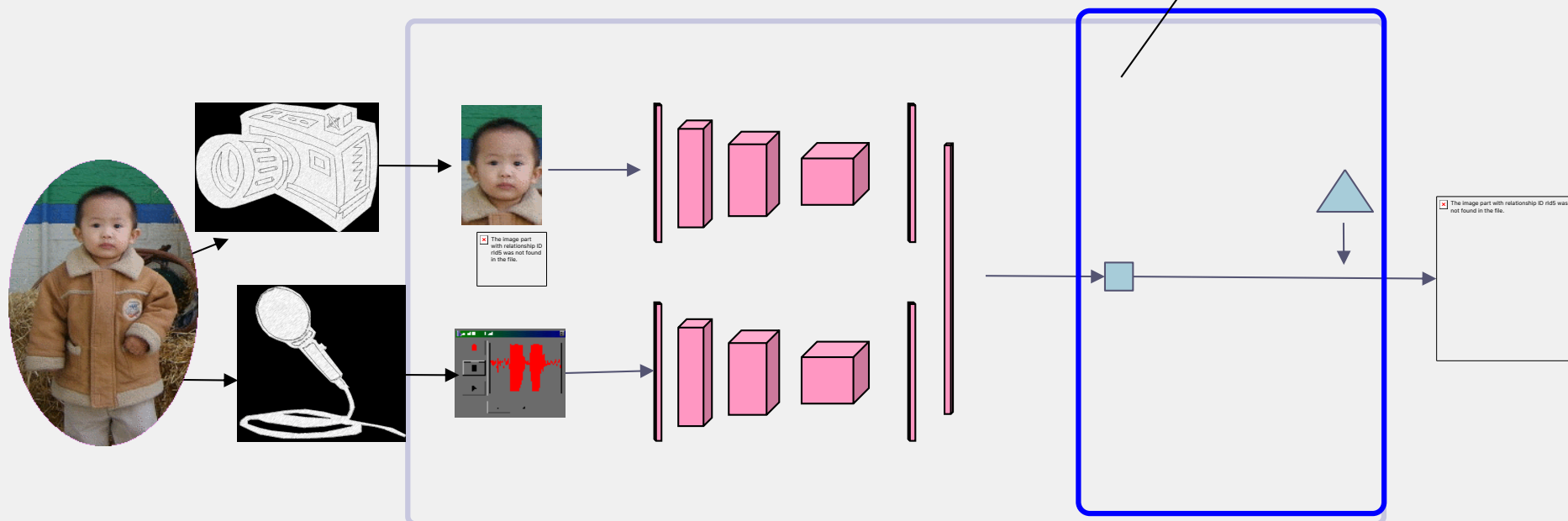


Data
Fusion

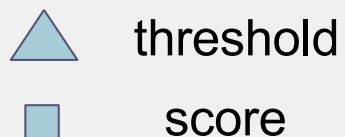
less information to deal with

Feature level fusion

$$\mathbf{y} = [y_1, \dots, y_N]$$



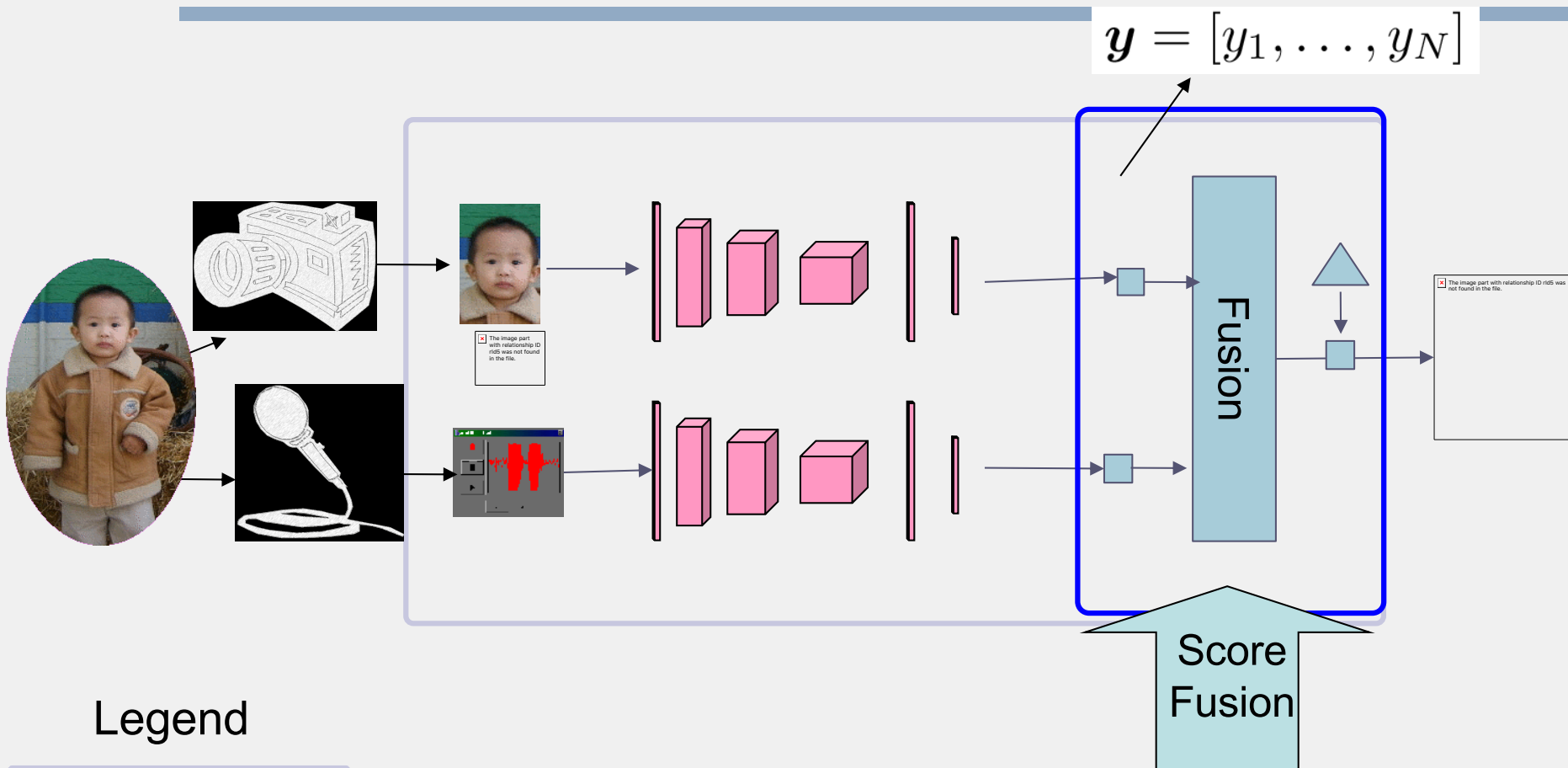
Legend



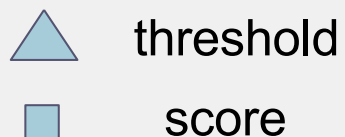
Feature
Fusion

less information to deal with

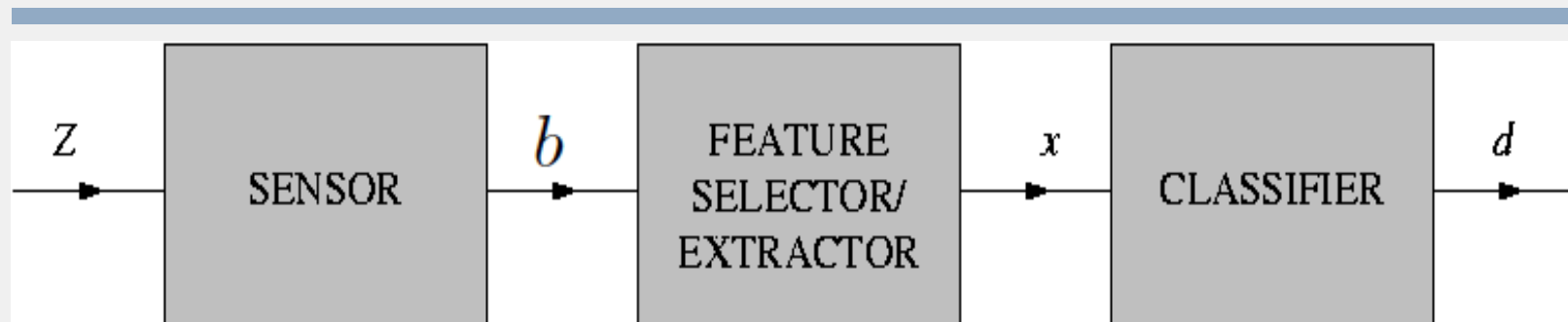
Score level fusion



Legend



Biometric system



Pattern recognition problem

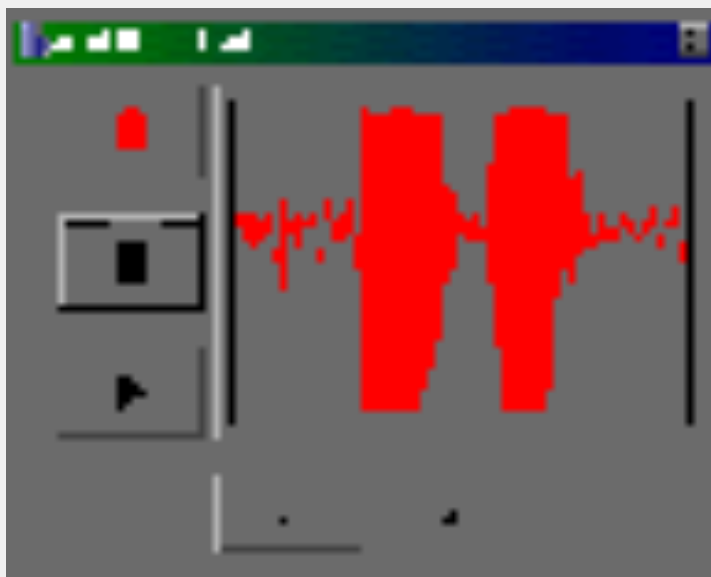
N – number of classes

b - biometric trait

x - feature vector

$P(\theta)$ -priori probability of class θ

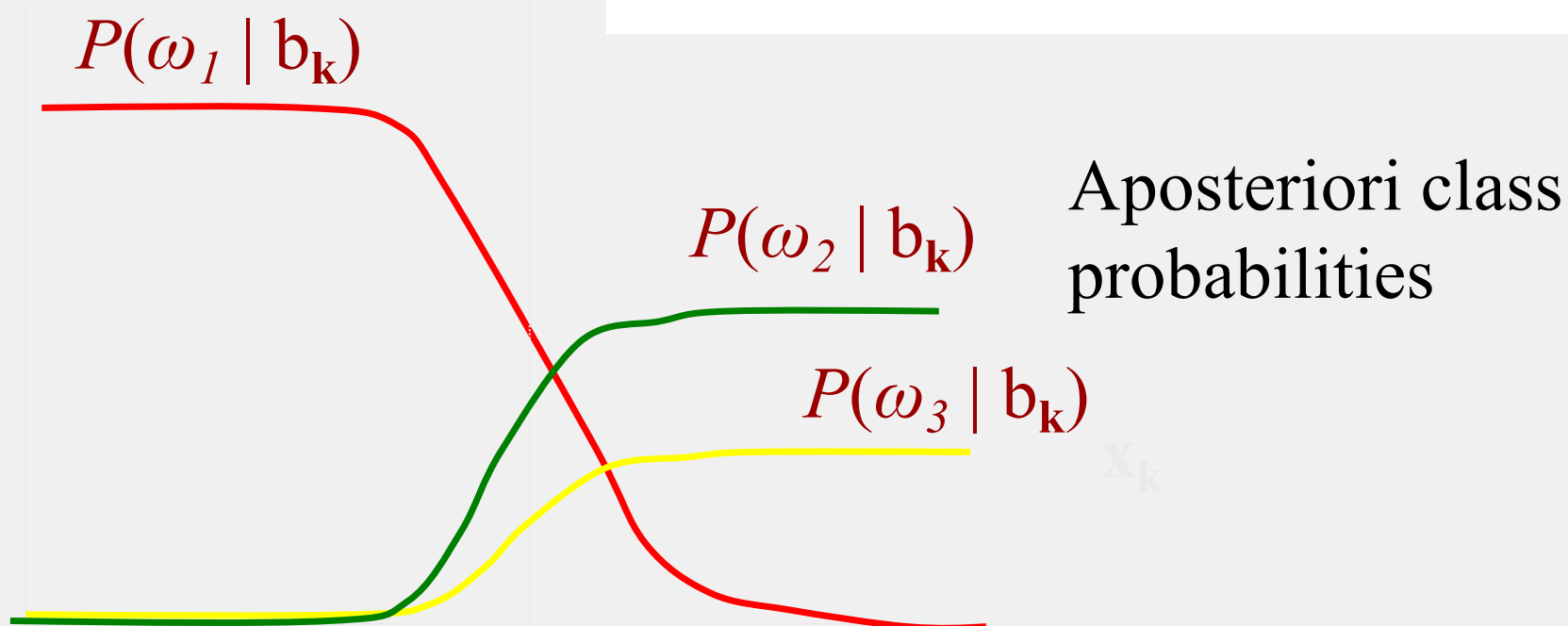
$p(x_k|\theta)$ -measurement distributions of patterns in class θ
 $p(b_k|\theta)$



Bayesian decision making

Bayes minimum
Error rule

$$b_k \rightarrow \omega \text{ if} \\ P(\omega|b_k) = \max_{\theta} P(\theta|b_k)$$



Problem formulation

- Given biometric traits: $[b_1, \dots, b_K]$
biometric features: $[x_1, \dots, x_K]$
identities: $[\theta_1, \dots, \theta_R]$

- Bayes decision rule

- *Assign* subject *to class* θ *if*

$$P(\omega | b_1, \dots, b_K) = \max P(\theta | b_1, \dots, b_K)$$

- Note

$$P(\omega | b_1, \dots, b_K) \propto \frac{p(b_1, \dots, b_K | \omega) P(\omega)}{\text{normalisation factor}}$$

Fusion options

■ Signal level fusion

$$\begin{aligned} p(b_1, \dots, b_K | \omega) &\propto \int_x p(x, b_1, \dots, b_K, \omega) \propto \\ &\propto \int_x P(\omega | x) p(x | b_1, \dots, b_K) \\ &\propto \hat{P}(\omega | x) \end{aligned}$$

■ The integration over x is marginalisation over the distribution $p(x | b_1, \dots, b_K)$

- x is a feature vector determined by all traits
- Implicitly a multiple classifier fusion
 - Bagging, boosting, drop out, hard sample mining

■ Marginalised estimate of class posterior $\hat{P}(\omega | x)$

Fusion options

■ Feature level fusion

$$\begin{aligned} p(b_1, \dots, b_K | \omega) &\propto \int_{x_1, \dots, x_K} p(x_1, \dots, x_K, b_1, \dots, b_K, \omega) \propto \\ &\propto \int_{x_1, \dots, x_K} P(\omega | x_1, \dots, x_K) p(x_1, \dots, x_K | b_1, \dots, b_K) \\ &\propto \hat{P}(\omega | x_1, \dots, x_K) \end{aligned}$$

- Each modality has its own set of features x_i
- Score is a function of all x_i jointly
- Fusion process marginalisation is over the joint distribution of all modalities
- In addition, there could be modality specific marginalisation at the feature extraction level

Fusion options

- Score level fusion

$$\begin{aligned} p(b_1, \dots, b_K | \omega) &\propto \prod_i \int_{x_i} p(x_i, b_i, \omega) \propto \\ &\propto \prod_i \int_{x_i} P(\omega | x_i) p(x_i | b_i) \\ &\propto \prod_i \hat{P}(\omega | x_i) \end{aligned}$$

- Each modality has its own set of features x_i
- The fused score is a product of individual modality specific scores
- Fusion process marginalisation is over modality specific distributions

- basic score level fusion is by product
- product can be approximated by a **sum** if $\hat{P}(\theta|x_k)$ does not deviate much from $P(\theta)$
i.e. $\hat{P}(\theta|x_k) = P(\theta) + \Delta_k$
- the resulting decision rule becomes

$$\begin{aligned} p(b_1, \dots, b_K | \omega) &\propto \prod_k \hat{P}(\omega | x_k) \\ &\propto \sum_k \hat{P}(\theta | x_k) \end{aligned}$$

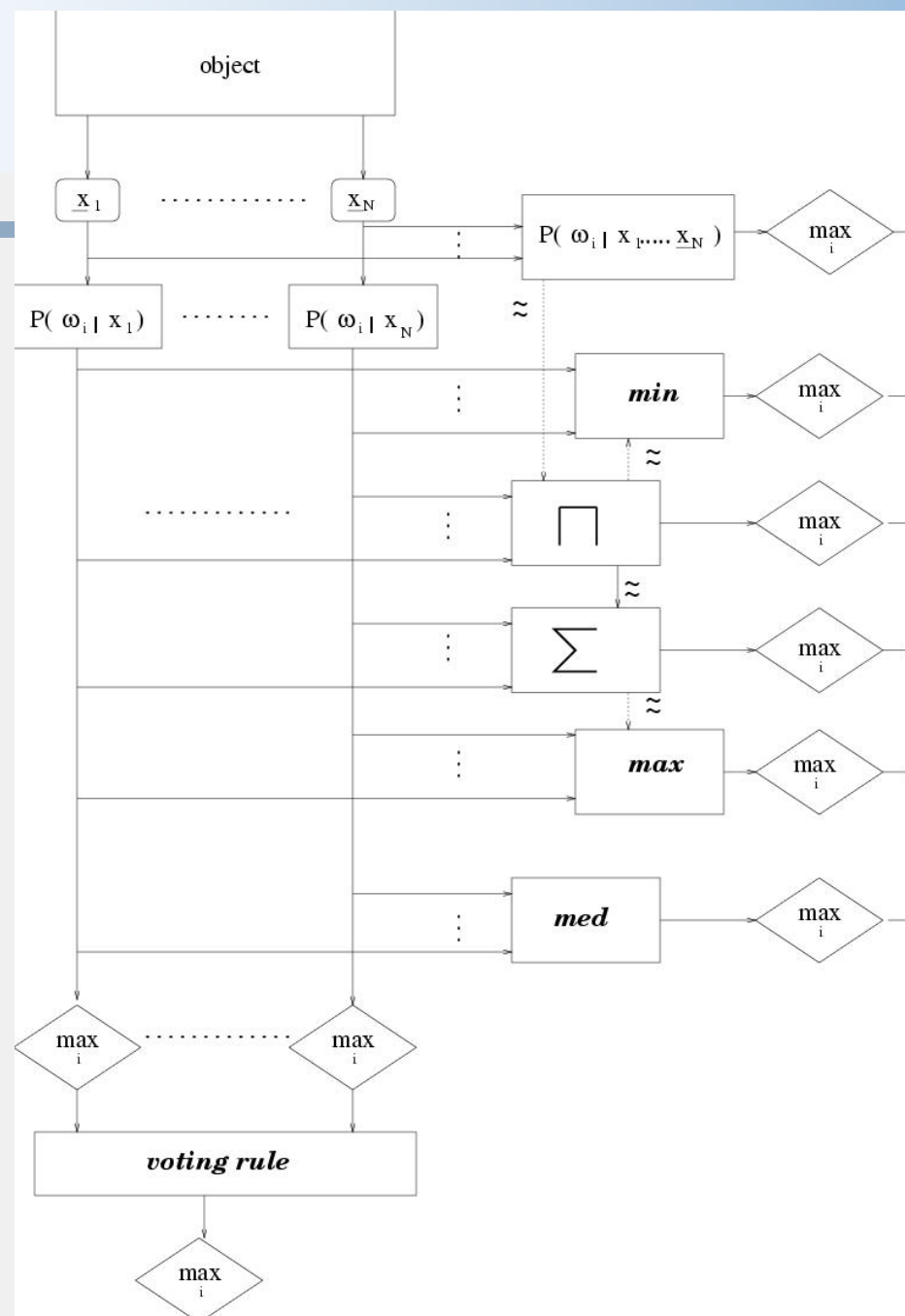
Fusion options

- Decision level fusion
 - Builds on score level fusion
 - Different fusion rules (rank, vote, ect)
- Example: Vote fusion
 - Each modality produces a hard decision

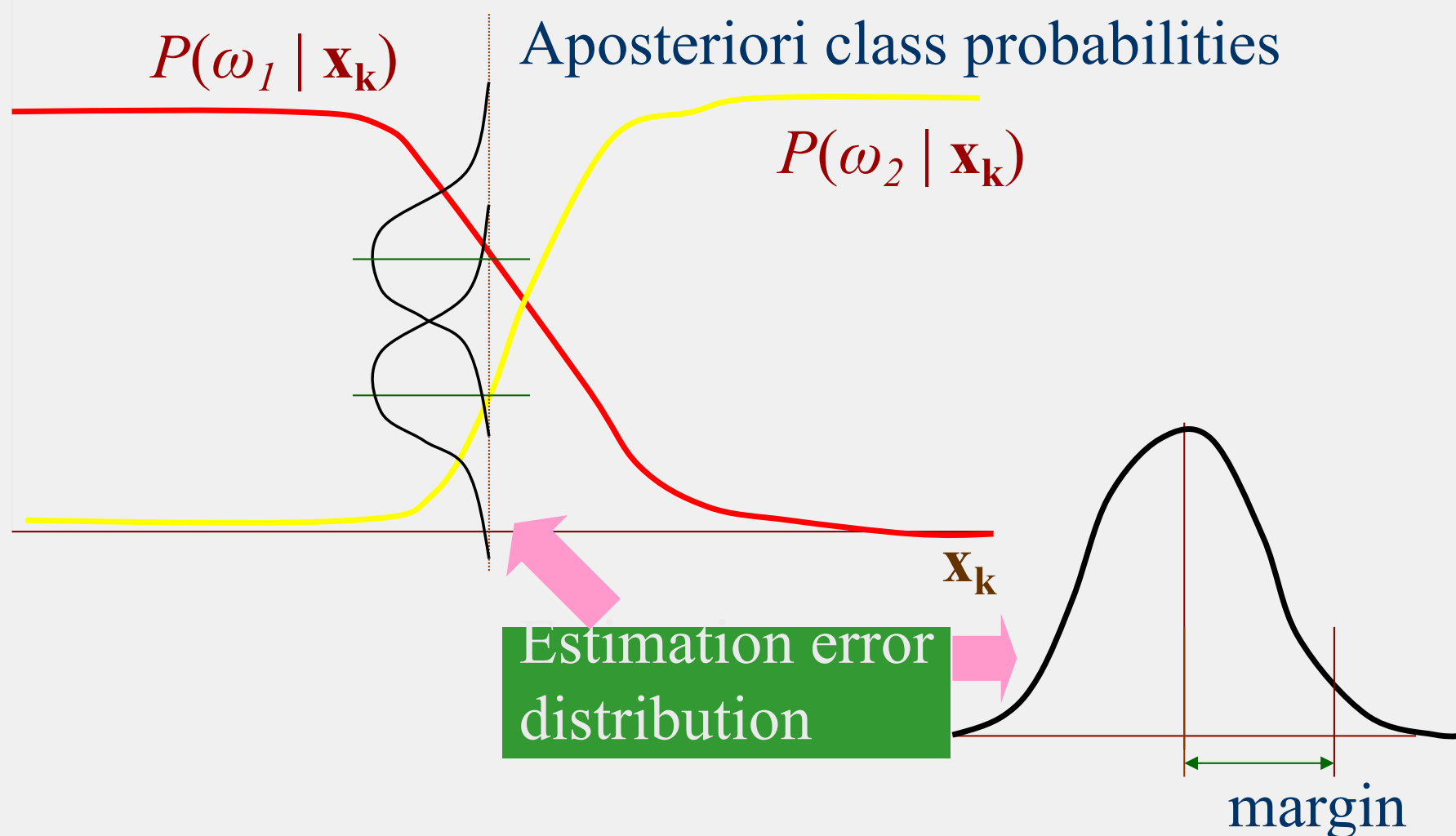
$$b_i \rightarrow \theta(i) \text{ if } \theta(i) = \max \arg_{\gamma} \hat{P}(\gamma|x_i)$$

- n_{θ} - the count of modalities outputting θ
- Final decision $[b_1, \dots, b_K] \rightarrow \omega \text{ if } n_{\omega} = \max_{\theta} n_{\theta}$
- In a two class case, a hard decision is made by comparing the score against a threshold

Fixed fusion strategies



Effect of estimation errors



$$\tilde{P}(\omega|\mathbf{x}_i) = \int \int P(\omega|\mathbf{x}_i, X_i, M, \gamma_i) p(M) p(\gamma_i) dM d\gamma_i$$

 \mathbf{x}_i

Feature vector output by sensor i

 X_i

Training set for the i-th expert

 M

Classifier model

 $p(M)$

Distribution of models

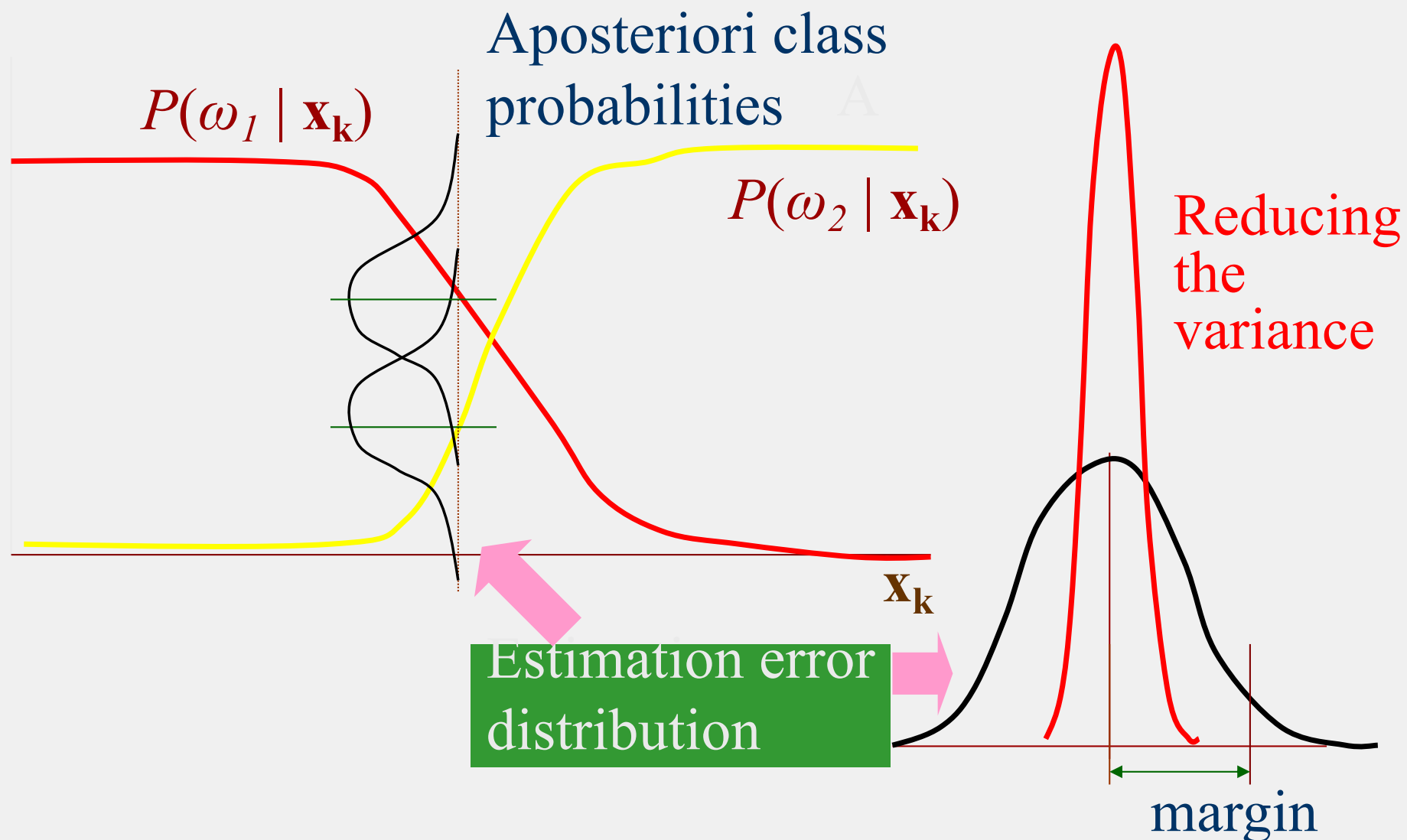
 γ_i

Parameters for expert i

 $p(\gamma_i)$

Distribution of expert i parameter

Coping with estimation errors



Variance reduction

- Consider a vector of normalised scores

$$\hat{\mathbf{s}} = [\hat{s}_1, \hat{s}_2, \dots, \hat{s}_R]^T$$

- with mean

$$\mu_k = [\mu_{k1}, \mu_{k2}, \dots, \mu_{kR}]^T, \quad k = c, i$$

- and covariance matrix

$$\Sigma_k = \begin{bmatrix} \sigma_{k11} & \cdot & \cdot & \cdot & \sigma_{k1R} \\ \sigma_{k21} & \sigma_{k22} & \cdot & \cdot & \sigma_{k2R} \\ \cdot & & & & \\ \cdot & & & & \\ \cdot & & & & \\ \sigma_{kR1} & \sigma_{kR2} & \cdot & \cdot & \sigma_{kRR} \end{bmatrix}$$

Variance reduction

- Fuse scores by $\hat{S} = \frac{1}{R} \sum_{j=1}^R \hat{s}_j$
- Average class conditional variance

$$\bar{\sigma}_k = \frac{1}{R} \sum_{j=1}^R \sigma_{kjj}$$

- Variance of fused score

$$\hat{\sigma}_k = E\{(\hat{S} - \hat{\mu}_k)^2\} = E\left\{\left[\frac{1}{R} \sum_{j=1}^R (\hat{s}_{kj} - \mu_{kj})\right]^2\right\}$$

Variance reduction

- Rearranging

$$\hat{\sigma}_k = E\left\{\frac{1}{R^2}\left[\sum_{j=1}^R (\hat{s}_{kj} - \mu_{kj})^2 + 2 \sum_{j=1}^R \sum_{i>j}^R (\hat{s}_{kj} - \mu_{kj})(\hat{s}_{ki} - \mu_{ki})\right]\right\}$$

- Variance can be bounded

$$\frac{1}{R}\bar{\sigma}_k \leq \hat{\sigma}_k \leq \bar{\sigma}_k$$

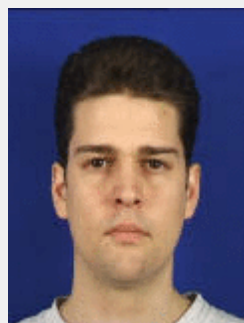
$$0 \leq \hat{\sigma}_k \leq \bar{\sigma}_k$$

- For uncorrelated scores - variance reduces by a factor of R
- For negatively correlated scores – variance can be brought to zero
- For negatively correlated scores the variance drops most when

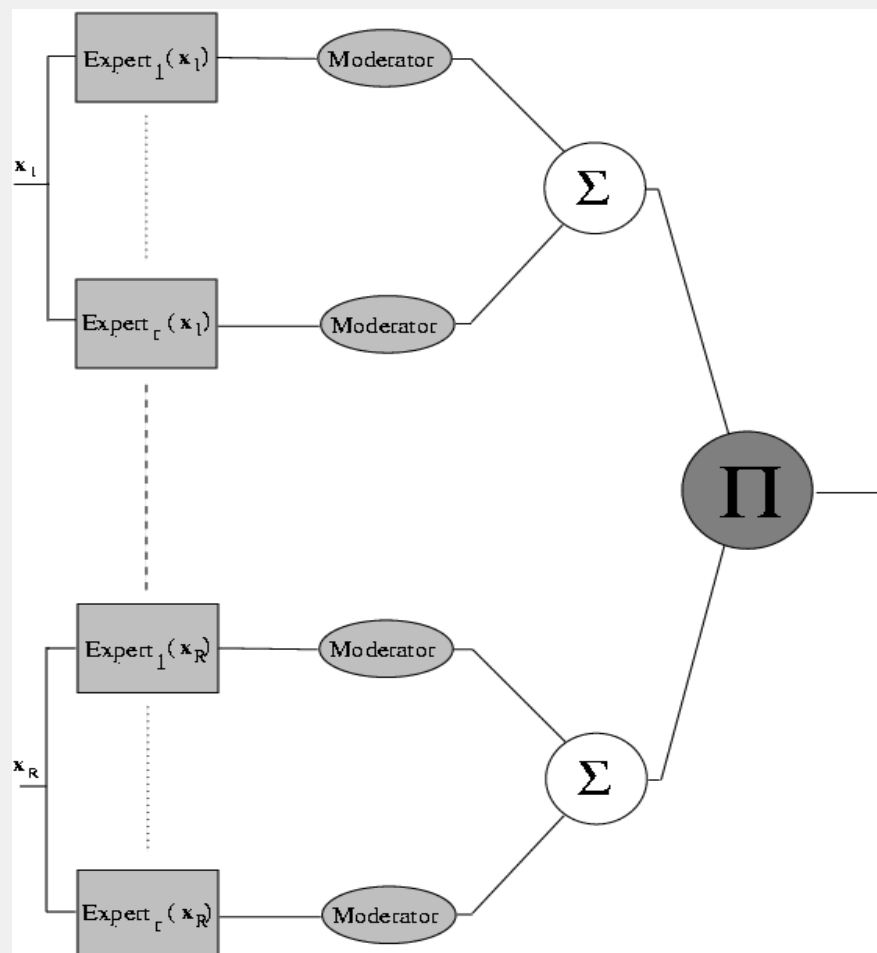
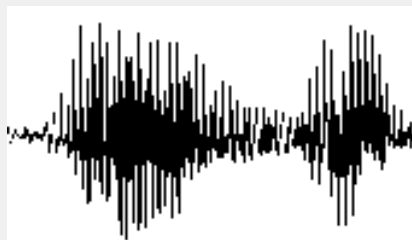
$$\sigma_{ii} = \sigma_{jj} \quad \forall j$$

Biometric Personal Identity Authentication

FACE



VOICE



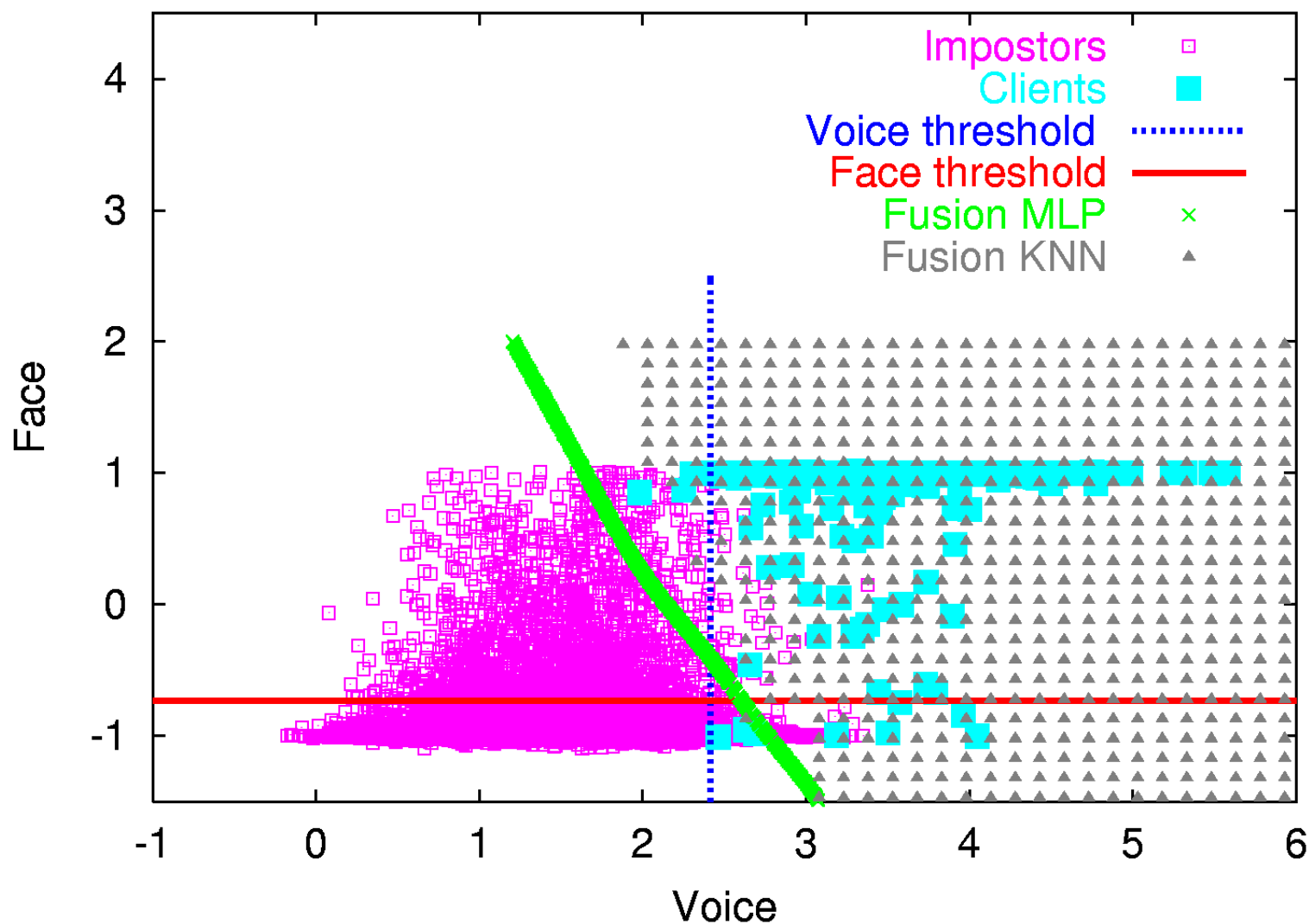
Fusion of face and voice

Performance of individual and fused experts

Toy example

Modalities	Performance		
	FAR	FRR	HTER
Face	1.75	2.00	1.88
Voice	1.47	1.00	1.23
Fusion SVM	0.32	0.25	0.28
Fusion MLP	0.34	0.25	0.29

Merits of multimodal fusion



Fusion strategies

- simple rules (sum, product, max, min, rank)
- trained fusion rule (logistic regression, decision templates, sparse based representation, svm, deep architectures)
- multistage systems (stacking)
- machine learning tools
 - Separability measures
 - Feature selection
 - Clustering
 - Distance metric
 - Classification

Direct score fusion: score normalisation

- Aposteriori class probabilities are automatically normalised to $[0,1]$
- Some systems compute a matching score s_i , rather than $P(\omega_i|\mathbf{x})$
- Scores have to be normalised to facilitate fusion by simple rules
 - aposteriori probability estimate

$$P(\omega_i|s) = \frac{p(s|\omega_i)P(\omega_i)}{\sum_{k=1}^R p(s|\omega_k)P(\omega_k)}$$

- Motivation for score normalisation
 - Non-homogeneous scores (distance, similarity)
 - Different ranges
 - Different distributions
- Desirable properties
 - Robustness
 - Efficiency
- Most effective methods
 - Nonlinear mapping with saturation for very large/small scores
 - Increased sensitivity near the boundaries (Ross and Jain)

Score normalisation (cont)

■ Min-max

$$\hat{s} = \frac{s - \min s}{\max s - \min s}$$

■ Scaling

$$\hat{s} = \frac{s}{\max s}$$

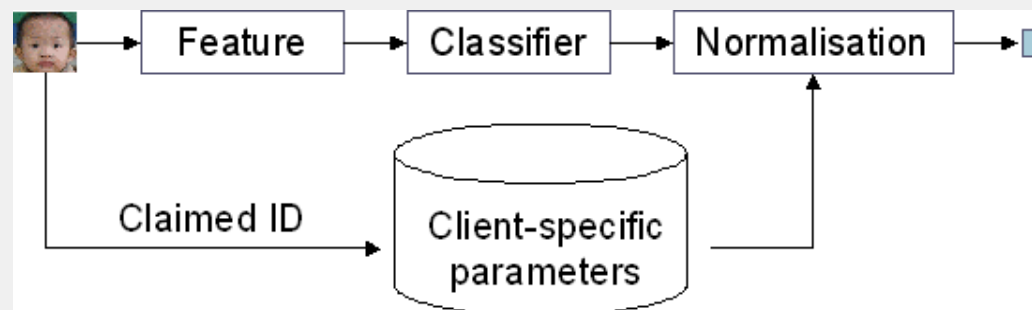
■ Z-score

$$\hat{s} = \frac{s - \mu}{\sigma}$$

μ and σ are the mean and standard deviation of the score distribution,

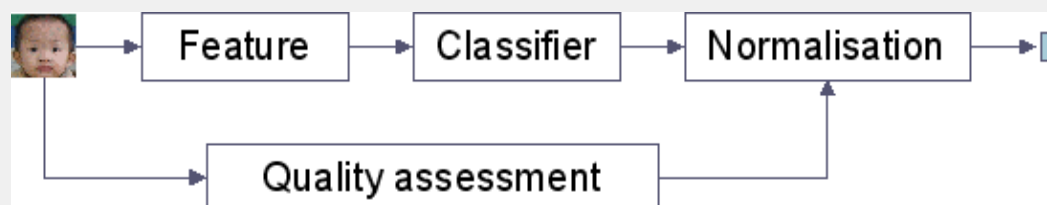
Information sources

Client/user-specific
normalization
(offline)



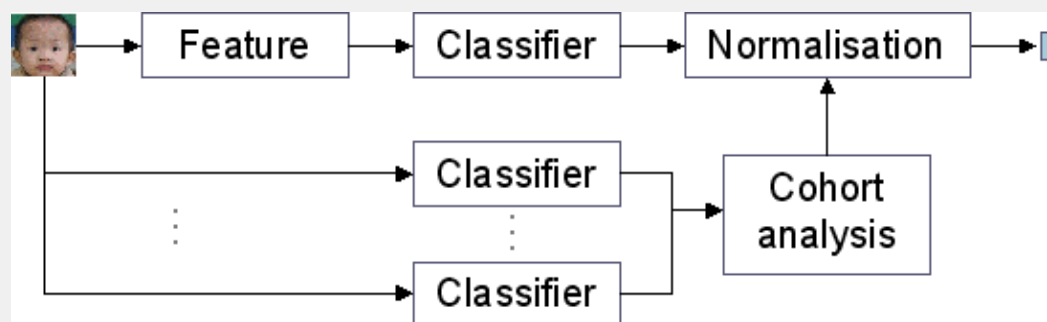
User-
dependent
score
characteristics

Quality-based
normalization



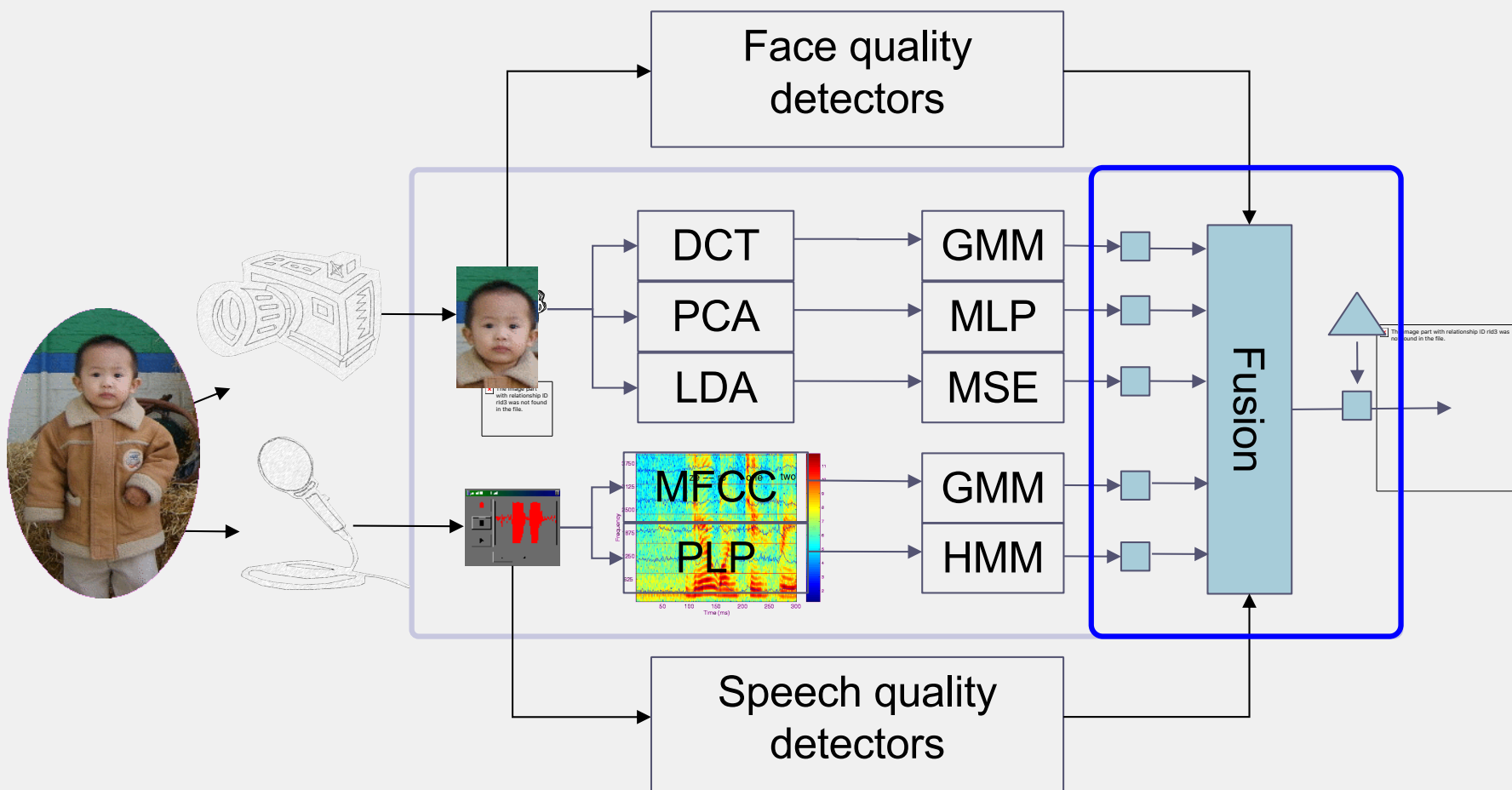
Changing
signal quality

Cohort-based
normalization
(online)



Changing
signal quality

Confidence-based Fusion Algorithms



Generative & Discriminative Approaches in QDF

Generative	$y_{com}^{llr} \equiv f^{llr}(x, q) = \log \frac{p(x, q C)}{p(x, q I)}$	e.g. GMM
Discriminative (probability-based)	$y_{com}^{prob} \equiv f^{prob}(x, q) = P(C x, q)$	e.g. MLP logistic regression
Discriminative (function-based)	$P(C x, q) \approx \text{sigmoid}(f^{disc}(x, q)) = \frac{1}{1 + \exp(-f^{disc}(x, q))}$	e.g. SVM, MLP

Algorithm used in experiments
 x and q are vectors

Case study in multimodal soft biometric fusion

- Multimodal biometric traits
- Multimodal sensing of the same biometric trait
 - Different spectral bands
 - Voice/image sensed lips dynamics
 - Visual/language modalities for person re-identification

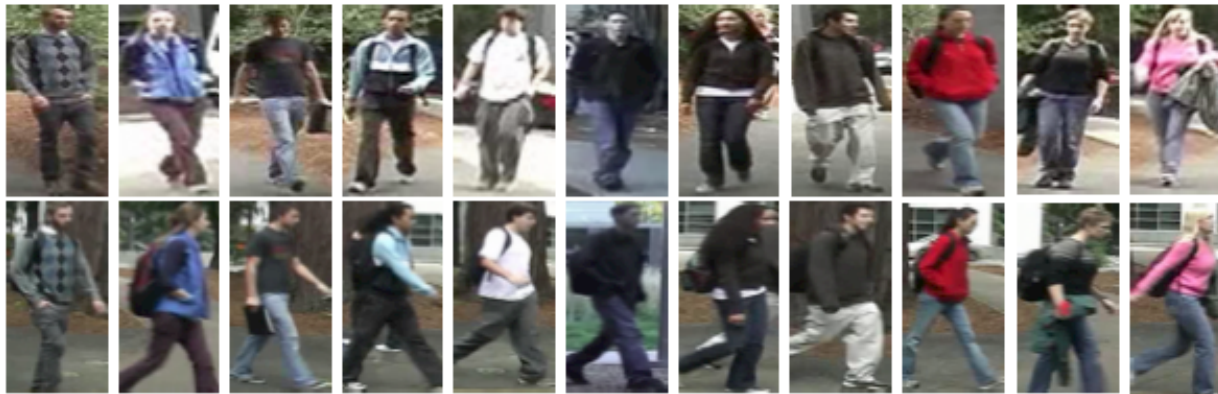
Background and motivation

- Video surveillance very important tool for crime prevention and detection
 - Watch list
 - Forensic video analysis
- Hard biometrics (face) not always available
- Other video analytics tools are useful alternatives
 - Soft biometrics (clothing, gait)
 - Tracking



Soft biometrics and re-identification

- **Person Re-Identification**
 - Recognising a person from non-overlapping cameras
- **Formulated as a ranking problem**



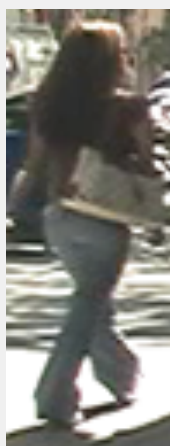
- **The majority of existing methods are vision only**
 - Images or videos
- **Joint vision and language modelling**
 - Image and video captioning, Visual question answering, Image synthesis from language, ...
- **Can language help vision in Re-ID?**

- **Augmenting existing datasets**
 - CUHK03: ~2700 descriptions
 - VIPeR: ~1300 descriptions
- **Crowd-sourced, 8 annotators**
- **Annotation**
 - Free style sentences, not attributes
 - Encouraged to cover details
 - On average 45 words per description
 - Per image rather than per identity

Language annotation



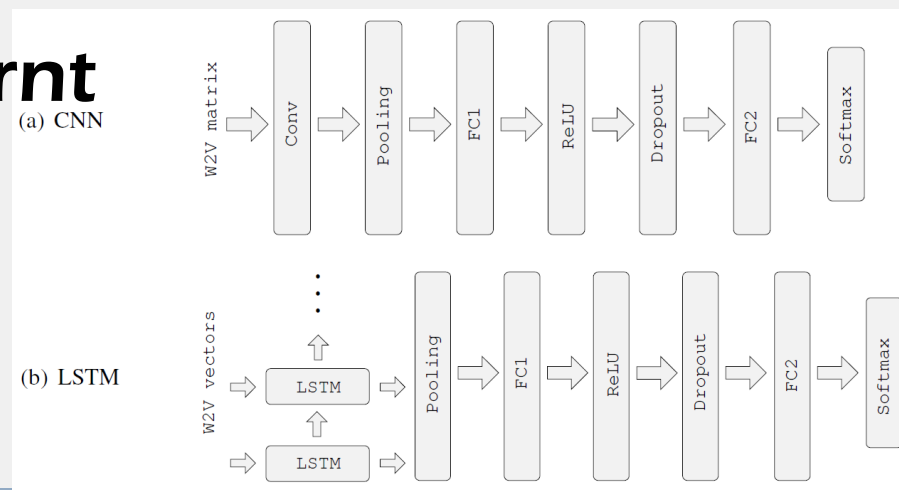
A front profile of a young, slim and average height, black female with long brown hair. She wears sunglasses and possibly earrings and necklace. She wears a brown t-shirt with a golden coloured print on its chest, blue jeans and white sports shoes.



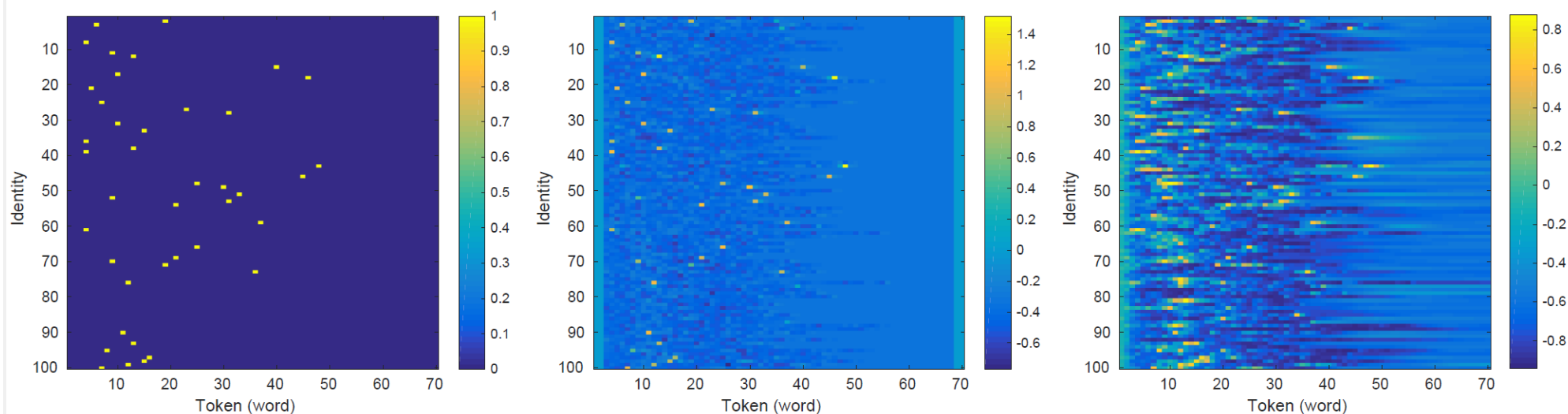
A short and slim young woman carrying a tortilla coloured rectangular shoulder bag with caramel straps, on her right side. She has a light complexion and long, straight auburn hair worn loose. She wears a dark brown short sleeved top along with bell bottomed ice blue jeans and her shoes can't be seen but she might be wearing light colored flat shoes.

Re-ID with language

- ResNet-50 for visual information
- Word2Vec embedding
- Neural networks: CNN and LSTM
- Multi-class setting, 2 examples per class (identity)
- Data augmentation
- Metric learning with learnt representations (XQDA)
- Canonical Correlation



Re-ID with language



- Detecting the concept of “spectacles”
 - “bespectacled”, “glasses”, “eye-glasses”, ...
 - GT, CNN, LSTM
 - One channel becomes “spectacles” detector during training
 - Good representation learnt from unstructured data

- Consider features x and y extracted from two biometric modalities
- Basic principle – find direction in the respective feature spaces that yield maximum correlation
 - Gauging linear relationship between two multidimensional random variables (feature vectors of two biometric modalities)
 - Finding two sets of basis vectors such that the projection of the feature vectors onto these bases is maximised
 - Determine correlation coefficients

CAA problem formulation

- Training set of pairs of vectors $(x_i, y_i), i = 1, n$
- Maximisation of the correlation of the projections

$$\begin{aligned} \max_{w_x, w_y} E\{w_x^T x y^T w_y\} &= \max_{w_x, w_y} w_x^T C_{xy} w_y \text{ s.t.} \\ E\{w_x^T x x^T w_x\} &= w_x^T C_{xx} w_x = 1 \\ E\{w_y^T y y^T w_y\} &= w_y^T C_{yy} w_y = 1 \end{aligned}$$

- Leads to an eigenvalue problem

$$\begin{aligned} \begin{bmatrix} 0 & C_{xy} \\ C_{yx} & 0 \end{bmatrix} \begin{bmatrix} w_x \\ w_y \end{bmatrix} &= \\ = \lambda \begin{bmatrix} (1 - \kappa)C_{xx} + \kappa I & 0 \\ 0 & (1 - \kappa)C_{yy} + \kappa I \end{bmatrix} \begin{bmatrix} w_x \\ w_y \end{bmatrix} \end{aligned}$$

- With cov matrices regularised by κI

- **Three sets:**
 - Training, query, gallery
 - Training: image and language pairs
- **Various settings, query x gallery:**
 - $V \times V, L \times L, V \times L, V \times VL, VL \times VL$
- **Asymmetric settings:**
 - Transfer language info. With CCA
- **XQDA as metric learning**

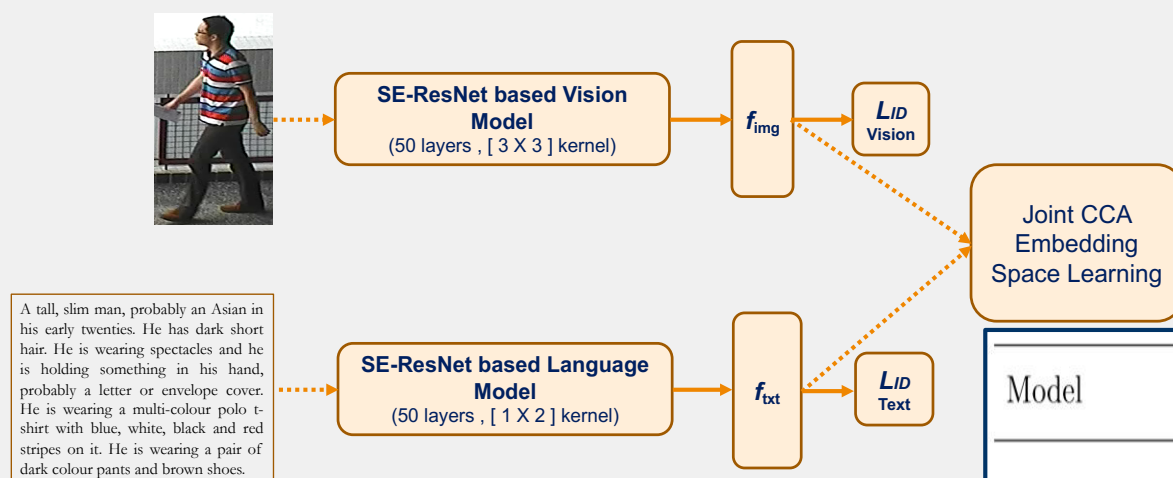
Re-ID with V&L

Gated CNN		68.1	88.1	94.6
Ours	V x V	70.3	93.2	96.6
	L x L	41.1	69.8	82.5
	V x L	17.7	48.5	66.0
	V x VL	73.5	94.5	97.7
	VL x VL	81.8	98.1	99.3

- Results on CUHK03, R1, R5, R10
- LxL worse than VxV: more information in vision
- VxVL 3.2 points higher than VxV
- VLxVL 12.7 points higher than VxV, better than state-of-the-art
- Language helps

Person Re-ID

■ Crossmodal & multimodal matching facilitated by CAA



■ Performance gain due to

- Joint training
- Fusion of modalities

Model	Rank@1 (%)	Rank@5 (%)	Rank@10 (%)	mAP (%)	medR
V × V					
Separately Train	59.91	80.5	85.7	64.45	1
Jointly Train + CCA	82.05	94.3	96.8	84.75	1
L × V					
Separately Train	13.6	32.99	43.04	18.5	15
Jointly Train + CCA	27.9	50.6	60.7	33.4	5
VL × V					
Separately Train	65.87	84.19	88.9	64.8	1
Jointly Train + CCA	84.7	95.0	97.1	84.1	1
VL × VL					
Separately Train	68.0	84.7	89.58	71.8	1
Jointly Train + CCA	80.86	94.16	96.6	83.85	1

Take home message

- Role of multimodal biometrics
- Fusion levels
- Math formulation of different alternatives
- The concept of marginalisation/multiple classifier systems
- Notion of quality based, user specific and cohort based extensions of fusion
- Multimodal sensing and fusion of a single biometric
- Example: fusion of vision/language modalities for soft biometrics

References

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